

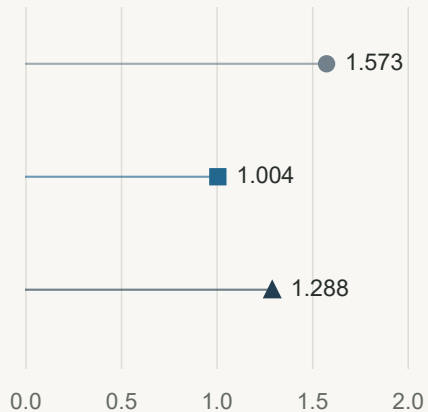
Episode duration

% of horizon · higher is better



Mean overload excess

$\times 10^{-3}$ · lower is better



Time overloaded

% of observed steps · lower is better

